

# DBScan

- It is a Density based clustering (Density-based spatial clustering of applications with noise)
- In density based clustering we partition points into dense regions separated by not-so-dense regions.
- DBScan works well even if your data contains non-convex clusters or noise.
- In DBSCAN, there are no centroids, and clusters are formed by linking nearby points to one another.
- **Important things in DBScan**
- **Parameters**
- Eps
- Minpoints
- **Types of data points**
- Core point
- Border point
- Noise or Outlier

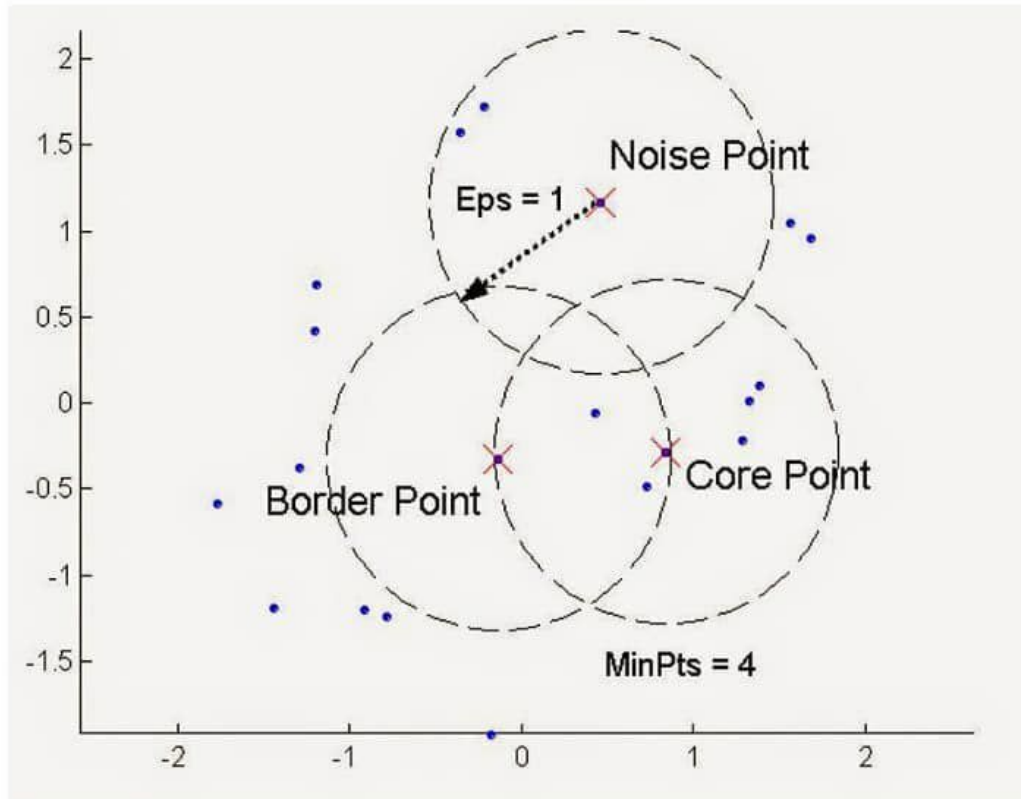
# DBScan

- **eps:** It defines the neighborhood around a data point i.e. if the distance between two points is lower or equal to 'eps' then they are considered as neighbors.
- If eps is small, then large no of points will be left out as noise
- If eps is large, then most of the points will be in same cluster
- We can find the best eps value using k-distance graph.

# DBScan

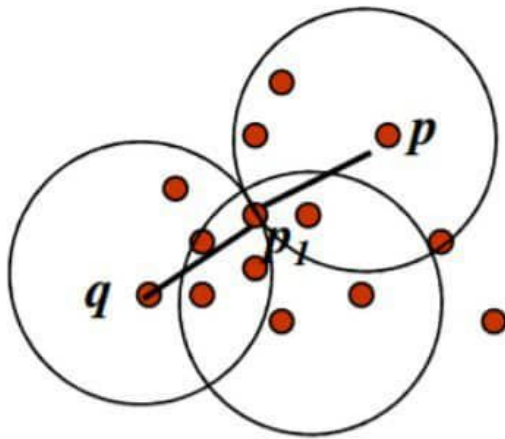
- **MinPoints:** Minimum number of data points within eps radius.
- Larger the dataset, the larger value of MinPts must be chosen.
- As a general rule, the minimum MinPts can be derived from the number of dimensions  $D$  in the dataset as,  
MinPts  $\geq D+1$ .
- Or MinPts =  $2*D$

# DBScan

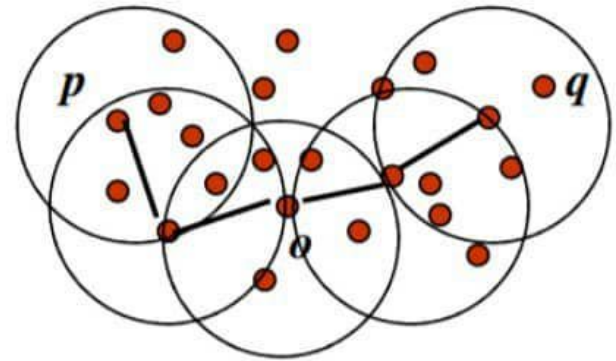


- **Core Point:** A point is a core point if it has more than  $\text{MinPts}$  points within  $\text{eps}$ .
- **Border Point:** A point which has fewer than  $\text{MinPts}$  within  $\text{eps}$  but it is in the neighborhood of a core point.
- **Noise or outlier:** A point which is not a core point or border point.

# DBScan



**Density edge**



**Density connected**

- **Density connected points**
- **Density edge:** We place an edge between two core points  $q$  and  $p$  if they are within distance  $\epsilon_{ps}$ .
- **Density-connected:** A point  $p$  is density-connected to a point  $q$  if there is a path of edges from  $p$  to  $q$ .

# DBScan

- **steps**
- Label points as core, border and noise
- Eliminate noise points
- For every core point  $p$  that has not been assigned to a cluster
- Create a new cluster with the point  $p$  and all the points that are density-connected to  $p$ .
- Assign border points to the cluster of the closest core point

# DBScan

- **Pros**
- Resistant to Noise
- Can handle clusters of different shapes and sizes
- **Cons**
- Varying densities
- High-dimensional data
- sensitive to parameters